

Please replace the paragraph beginning at page 3, line 12, with the following rewritten paragraph:

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Among the objects of this invention is to provide a new and improved massage and tactile stimulation device in the nature of a hand covering such as a mitt, mitten, or glove worn upon the hand of the user, masseur, or therapist. More specifically, a glove having prominent projections of at least 0.14 inches (3.5 mm) in height, to facilitate deep and point specific pressure on the recipient, being with or without friction areas. These instrumentalities, secured at effective working areas on the device, provide for distinct and improved manipulations over the human hand.

Please replace the paragraph beginning at page 5, line 6, with the following rewritten paragraph:

A3
It will be obvious to those skilled in the art to which this invention appertains, that the same may be incorporated in several different constructions. It will be understood this device may be made in various sizes and different specific designs. It must be clearly understood that although each finger of the glove in Fig.1 is provided with a predetermined prominent projection for deep pressure, only one of the fingers may be provided with a projection. If desired, only a single finger tip can be used for applying deep pressure.

Please replace the paragraph beginning at page 5, line 15, with the following rewritten paragraph:

A4 Referring now more particularly to the drawing, illustrated is a device as comprising a glove 10 (FIG. 1). Glove 10 is made of any suitable resilient material of good quality such as lycra or spandex that will closely adhere to the anatomy of the hand. Glove 10 is made by sewing or the like, in the preferred embodiment.

Please replace the paragraph beginning at page 6, line 1, with the following rewritten paragraph:

A5 Projections 12 and 22 adhere to glove 10 and 20 by virtue of pressure sensitive adhesion or other method for bonding plastic to cloth, that provides stationary bonding. Projection 12 is secured to glove 10 at a first effective working area to optimize use. Projection 12 is located on the pad of each digit. Projection 22 is secured to glove 20 at a second effective working area. Projection 22 is located on the back of the first row of phalanges (proximal) to impart considerable force and pressure to the recipient when glove 20 is held in a clenched fist (FIG 6).

Please replace the paragraph beginning at page 6, line 11, with the following rewritten paragraph:

A6 The preferred embodiment includes friction areas 14 and 16 secured to glove 10 at effective working areas third and fourth, respectively. Area 14 is elliptical in shape

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cont'd

covering the palm pad of the thumb (thenar). Area 16 is circular in shape covering the pisiform bone located at base of the fifth digit pad (hypothenar). Adhered to glove 10 by the same method as projections 12 and 22, areas 14 and 16 are made of a rubber-like material with a sufficient coefficient of friction to facilitate improved manual manipulations such as grasping and frictional rubbing. Areas 14 and 16 are secured to glove 10 at effective working areas such as the palm region, between the thumb and index finger (not shown), and lateral fifth digit region (not shown). Areas 14 and 16 enhance manual manipulations over the human hand.

Please replace the paragraph beginning at page 6, line 20, with the following rewritten paragraph:

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It will be understood that the device may be made in various sizes, varied or different specific designs, and for application to either hand of the manipulator. It is self evident with the device as illustrated, the projections (FIG. 2, 3, 4 and 5) and friction areas (FIG. 1) can be of various shapes, predetermined sizes, colors, forms, and textures. Examples of additional shapes include cone shaped projection 18 with an indentation 19 (FIG. 3) and canal shaped projection 24 (FIG. 5). They can be varied on the same glove, as well. Both can be secured to the glove at various effective working areas to maximize function of device and assistance to the manipulator.

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4 14

Please replace the paragraph beginning at page 8, line 1, with the following rewritten paragraph:

AS An improvement can include a rubber-like glove with a breathing mechanism, to decrease moisture on the hand, made by molding or the like. The glove and its instrumentalities, can be made of a rubber-like material that can be easily disposed of or cleaned for sanitary use in a healthcare setting, increasing its use in settings with multiple clients.